

ELECTROMAGNETIC THEORY.

(1)

Electromagnetics is a branch of physics which is used to study electric and magnetic phenomena.

Field can be defined as the region in which, at each point there exists a corresponding value of some physical function.

Eg: magnet.

If the field produced due to magnetic effects is called magnetic field.

There are two types of charges +ve and -ve. Such an electric charge produces a field around is called an electric field.

Moving charges produce a current & current carrying conductors produces a magnetic field. In such case electric & magnetic fields are related to each other. Such a field is called electromagnetic field.

The comprehensive study of characteristics of electric, magnetic & combined fields is nothing but the engineering electromagnetics. Such fields may be time varying or time independent.

The distribution of a quantity in a space is defined by a field. Hence to quantify the field, three dimensional representation plays an important role. Such a three dimensional representation can be made easy by the use of vector analysis.

The two quantities which are involved in electromagnetism are : Scalar & vector

Scalar : - is a quantity which has only magnitude & no direction
 eg : temperature, mass, volume etc..

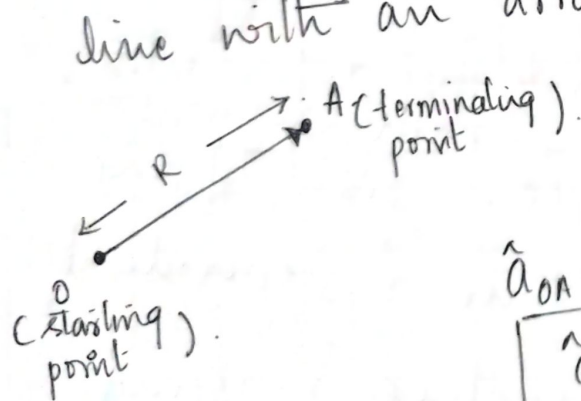
vector : - is a quantity which has both magnitude & direction
 eg : force, velocity etc..

The distribution of a scalar quantity with a definite position in a space is called scalar field.
 eg : temperature in atmosphere.

If a quantity which is specified in a region to define a field is a vector then it is called vector field.

eg : gravitational force on a mass in a space.

Representation of a vector : - In two dimensions, a vector can be represented by a straight line with an arrow in a plane.



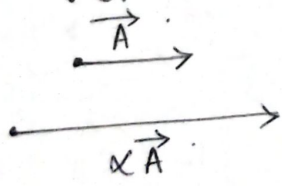
$$\vec{OA} = |\vec{OA}| \hat{a}_{OA}$$

$|\vec{OA}| = R = \text{magnitude of the vector}$

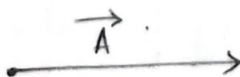
$\hat{a}_{OA} = \text{unit vector which defines the direction}$

$$\boxed{\hat{a}_{OA} = \frac{\vec{OA}}{|\vec{OA}|}}$$

* Scaling of vector

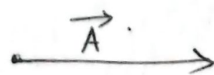


$[\alpha > 1]$



$$\alpha \vec{A}$$

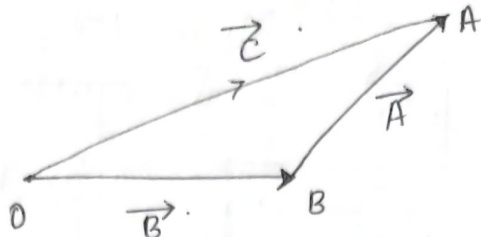
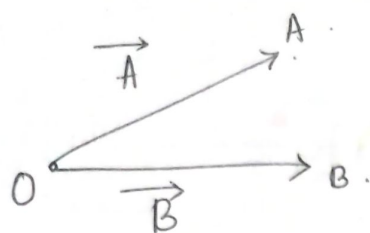
$[\alpha < 1]$



$$-\vec{A}$$

$[\alpha = -1]$

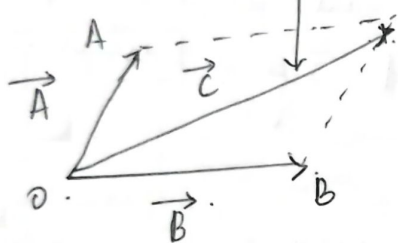
* Addition of vectors :- Consider two coplanar vectors. (2)
The vectors which lie in the same plane are called coplanar vectors :



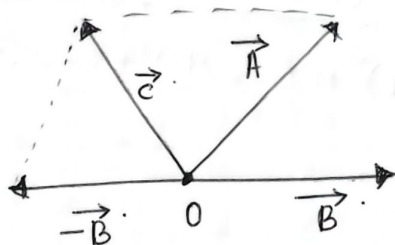
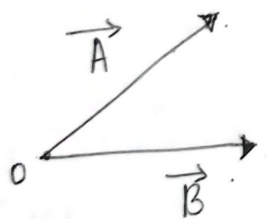
$$\vec{C} = \vec{A} + \vec{B}$$

It is remembered that the direction of \vec{C} is from origin O to the tip of the vector moved.

Another method of performing the addition of vectors is the parallelogram rule. The diagonal of the parallelogram represents the addition of two vectors.



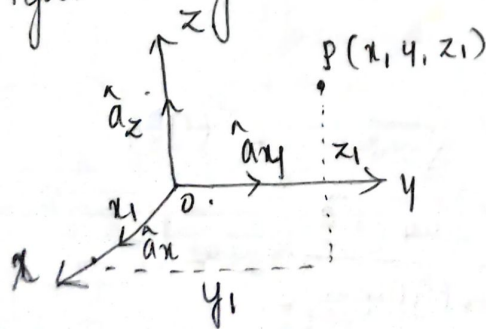
* Subtraction of vectors :- is obtained from the rules of addition



$$\vec{C} = \vec{A} - \vec{B}$$

* To describe a vector accurately we have three co-ordinate systems.

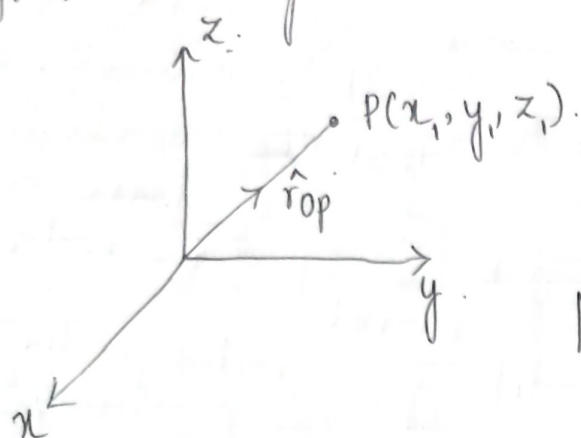
1. Cartesian co-ordinate system :- It has three co-ordinate axes represented as x, y and z which are mutually at right angles to each other.



If $x=0$, then plane indicates two dimensional $y-z$ plane.

Base vectors $\hat{a}_x, \hat{a}_y, \hat{a}_z$ are unit vectors which are strictly oriented along the direction of the co-ordinate axes.

Positional vector : - Considers a point $P(x_1, y_1, z_1)$ in a Cartesian co-ordinate system. Then the positional vector of point P is represented by the distance of point P from the origin. This is also called radius vector.

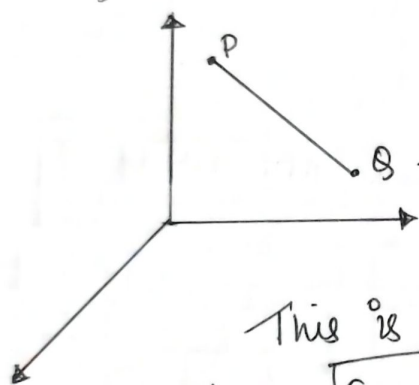


Then the positional vector at P is given by

$$\vec{r}_{OP} = x_1 \hat{a}_x + y_1 \hat{a}_y + z_1 \hat{a}_z$$

$$|\vec{r}_{OP}| = \sqrt{x_1^2 + y_1^2 + z_1^2}$$

Distance vector : - Considers two points in a Cartesian co-ordinate system P & Q with the co-ordinates $P(x_1, y_1, z_1)$ and $Q(x_2, y_2, z_2)$. Then the distance or displacement from P to Q is represented by a distance vector.



$$\vec{PQ} = \vec{Q} - \vec{P}$$

$$= (x_2 - x_1) \hat{a}_x + (y_2 - y_1) \hat{a}_y + (z_2 - z_1) \hat{a}_z$$

This is also called separation vector.

$$|\vec{PQ}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

$$\hat{a}_{PQ} = \frac{\vec{PQ}}{|\vec{PQ}|}$$

Ex: - Obtain the unit vector in the direction from the origin towards the point $P(3, -3, -2)$.

∴ - Origin = $(0, 0, 0)$
 $P = (3, -3, -2)$

$$\vec{OP} = (3-0) \hat{a}_x + (-3-0) \hat{a}_y + (-2-0) \hat{a}_z$$

$$\vec{OP} = 3 \hat{a}_x - 3 \hat{a}_y - 2 \hat{a}_z$$

$$|\vec{OP}| = \sqrt{3^2 + (-3)^2 + (-2)^2} = \sqrt{22} = 4.6904$$

$$\hat{a}_{OP} = \frac{\vec{OP}}{|\vec{OP}|} = \frac{3 \hat{a}_x - 3 \hat{a}_y - 2 \hat{a}_z}{4.6904}$$

$$\hat{a}_{OP} = 0.639\hat{a}_x - 0.639\hat{a}_y - 0.426\hat{a}_z \quad (3)$$

Ex 2) :- Two points A(2, 2, 1) and B(3, -4, 2) are given in Cartesian system, obtain the vector from A to B & a unit vector directed from A to B.

$$\therefore - \hat{a}_{AB} = \frac{\vec{AB}}{|\vec{AB}|}$$

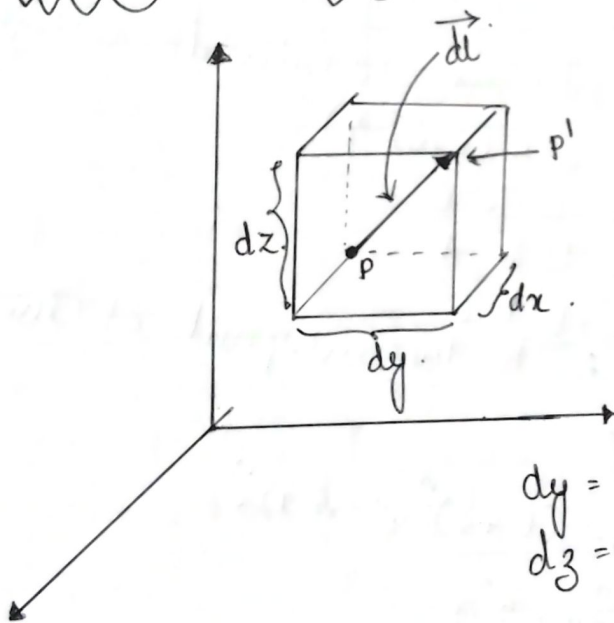
$$\vec{AB} = \vec{B} - \vec{A} = (3-2)\hat{a}_x + (-4-2)\hat{a}_y + (2-1)\hat{a}_z$$

$$\vec{AB} = \hat{a}_x - 6\hat{a}_y + \hat{a}_z$$

$$|\vec{AB}| = \sqrt{1^2 + (-6)^2 + 1^2} = \sqrt{38} = 6.1644$$

$$\hat{a}_{AB} = \frac{\hat{a}_x - 6\hat{a}_y + \hat{a}_z}{6.1644} = 0.162\hat{a}_x - 0.973\hat{a}_y + 0.162\hat{a}_z$$

Differential elements in Cartesian co-ordinate system



Consider a point $P(x, y, z)$ in the rectangular co-ordinate system. Let us increase each co-ordinate by a differential amount. A new point P' will be obtained having co-ordinates:

$$(x+dx, y+dy, z+dz)$$

dx = differential length in x-direction
 dy = differential length in y-direction
 dz = differential length in z-direction.

The distance of P' from P is given by magnitude of the differential vector length.

$$|\vec{dl}| = \sqrt{(dx)^2 + (dy)^2 + (dz)^2}$$

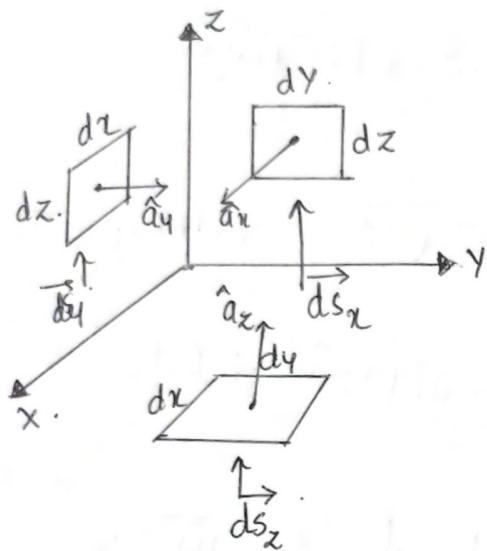
differential vector length is represented as

$$\vec{dl} = dx\hat{a}_x + dy\hat{a}_y + dz\hat{a}_z$$

differential volume, $dv = dx dy dz$.

Elemental Surface : - The differential element ds is represented as,
 $\vec{ds} = ds \hat{a}_n$.

where ds = differential surface area of the element.
 \hat{a}_n = unit vector normal to the surface ds .



\vec{ds}_x = differential vector surface area normal to x-direction
 $= dy dz \hat{a}_x$

\vec{ds}_y = differential vector surface area normal to y-direction
 $= dx dz \hat{a}_y$

\vec{ds}_z = differential vector surface area normal to z-direction
 $= dx dy \hat{a}_z$

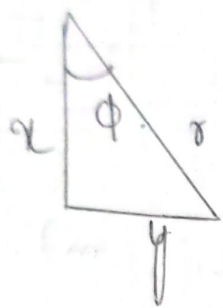
Ex. Given three points in Cartesian coordinate system as
 $A(3, -2, 1)$, $B(-3, -3, 5)$, $C(2, 6, -4)$.

- Find
- the vector from A to C
 - unit vector from B to A
 - the distance from B to C
 - the vector from A to the midpoint of the st. line joining B to C.

i) $\vec{AC} = \vec{C} - \vec{A} = (2-3)\hat{a}_x + (6+2)\hat{a}_y + (-4-1)\hat{a}_z$
 $= -\hat{a}_x + 8\hat{a}_y - 5\hat{a}_z$

ii) $\hat{a}_{BA} = \frac{\vec{BA}}{|\vec{BA}|} = \frac{\vec{A} - \vec{B}}{|\vec{A} - \vec{B}|} = \frac{(3+3)\hat{a}_x + (-2+3)\hat{a}_y + (1-5)\hat{a}_z}{\sqrt{6^2 + 1^2 + (-4)^2}}$
 $= \frac{6\hat{a}_x + \hat{a}_y - 4\hat{a}_z}{\sqrt{62}} = \frac{6\hat{a}_x + \hat{a}_y - 4\hat{a}_z}{7.2801}$

$\hat{a}_{BA} = \frac{\vec{BA}}{|\vec{BA}|} = 0.8241\hat{a}_x + 0.1373\hat{a}_y - 0.5494\hat{a}_z$



At XY plane,

$$\cos \phi = \frac{x}{r}, \quad \sin \phi = \frac{y}{r}.$$

$$\Rightarrow x = r \cos \phi - (1), \quad y = r \sin \phi - (2), \quad z = z.$$

$$\begin{aligned} \text{eq(1)}^2 + \text{eq(2)}^2 &\Rightarrow x^2 + y^2 = r^2 \sin^2 \phi + r^2 \cos^2 \phi \\ x^2 + y^2 &= r^2 [\sin^2 \phi + \cos^2 \phi] \\ x^2 + y^2 &= r^2 \\ r &= \sqrt{x^2 + y^2} \end{aligned}$$

$$\frac{\text{eq(2)}}{\text{eq(1)}} \Rightarrow \frac{r \sin \phi}{r \cos \phi} = \frac{y}{x}.$$

$$\tan \phi = \frac{y}{x}.$$

$$\phi = \tan^{-1}(y/x), \quad z = z.$$

Ex. A point P in space is identified with coordinates $P(3, 4, 6)$ mtr and another point Q $(2, 30^\circ, 4)$. Find

- the cylindrical co-ordinates of point P.
- cartesian co-ordinates of point Q.
- Find the distance from P to Q.

\therefore - i) $P(3, 4, 6)$

$$x = 3, \quad y = 4, \quad z = 6.$$

$$r = \sqrt{x^2 + y^2} = \sqrt{3^2 + 4^2} = \sqrt{9 + 16} = \sqrt{25} = 5.$$

$$\tan \phi = y/x \Rightarrow \tan \phi = 4/3 \Rightarrow \phi = \tan^{-1}(4/3) = 53.13^\circ.$$

$$z = 6.$$

ii) $Q(2, 30^\circ, 4)$.

$$r = 2, \quad \phi = 30^\circ, \quad z = 4.$$

$$x = r \cos \phi = 2 \cos 30^\circ = 1.73.$$

$$y = r \sin \phi = 2 \sin 30^\circ = 1.$$

$$z = z = 4.$$

iii) $P(3, 4, 6)$, $Q(1.73, 1, 4)$

$$|\overrightarrow{PQ}| = |\overrightarrow{Q} - \overrightarrow{P}| = \sqrt{(1.73-3)^2 + (1-4)^2 + (4-6)^2}$$

$$= 3.822$$

Ex: - A point is located at $P(4, 6, 8)$ & $Q(5m, 60^\circ, 3m)$.

- Find
- cylindrical coordinate of point P.
 - Cartesian co-ordinate of point Q.
 - distance from P to Q.

∴ - Ans. i) 7.211,
ii) 2.5,
iii) 5.5m.

Spherical Co-ordinate System :- Three coordinates at a point

P are r, θ, ϕ .
The unit vectors are $\hat{a}_r, \hat{a}_\theta, \hat{a}_\phi$.

The limits are -

$$0 \leq r \leq \infty$$

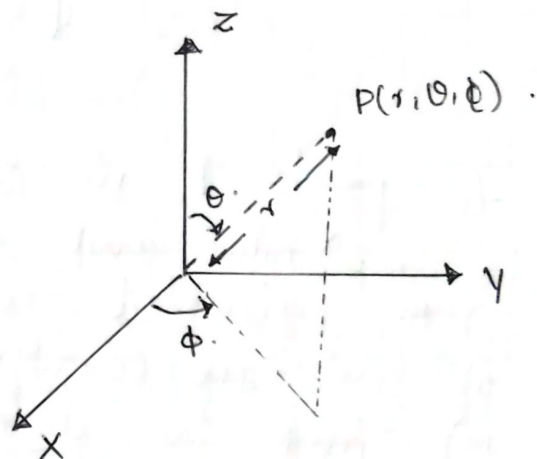
$$0 \leq \theta \leq 180^\circ$$

$$0 \leq \phi \leq 360^\circ$$

Differential vector length

$$d\vec{r} = dr\hat{a}_r + r d\theta\hat{a}_\theta + r \sin\theta d\phi\hat{a}_\phi$$

$$|d\vec{r}| = \sqrt{(dr)^2 + (r d\theta)^2 + (r \sin\theta d\phi)^2}$$



Differential volume

$$dv = r^2 \sin\theta dr d\theta d\phi$$

Differential surface

$$d\vec{s}_r = r^2 \sin\theta d\theta d\phi \hat{a}_r$$

$$d\vec{s}_\theta = r \sin\theta dr d\phi \hat{a}_\theta$$

$$d\vec{s}_\phi = r dr d\theta \hat{a}_\phi$$